Sample Paper for the aomart Class

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Abstract

This is a test file for aomart class based on the testmath.tex file from the amsmath distribution.

It was changed to test the features of the Annals of Mathematics class.

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1. Introduction

This paper demonstrates the use of aomart class. It is based on testmath.tex from \texttt{AMSTeX} distribution. The text is (slightly) reformatted according to the requirements of the aomart style. See also [12, 22, 17, 1, 16, 15, 24, 23, 6].

It is always a pleasure to cite Knuth [9].

2. Enumeration of Hamiltonian paths in a graph

Let $A = (a_{ij})$ be the adjacency matrix of graph $G$. The corresponding Kirchhoff matrix $K = (k_{ij})$ is obtained from $A$ by replacing in $-A$ each diagonal entry by the degree of its corresponding vertex; i.e., the $i$th diagonal entry is identified with the degree of the $i$th vertex. It is well known that

\[ \det K(i|i) = \text{the number of spanning trees of } G, \quad i = 1, \ldots, n \]

where $K(i|i)$ is the $i$th principal submatrix of $K$.

\[ \det(a_{ij})_{i \neq j} = \text{the number of spanning trees of } G \]

Let $C_{i(j)}$ be the set of graphs obtained from $G$ by attaching edge $(v_i, v_j)$ to each spanning tree of $G$. Denote by $C_i = \bigcup_j C_{i(j)}$. It is obvious that the collection of Hamiltonian cycles is a subset of $C_i$. Note that the cardinality of $C_i$ is $k_{ii} \det K(i|i)$. Let $\hat{X} = \{\hat{x}_1, \ldots, \hat{x}_n\}$.

Define multiplication for the elements of $\hat{X}$ by

\[ \hat{x}_i \hat{x}_j = \hat{x}_j \hat{x}_i, \quad \hat{x}^2_i = 0, \quad i, j = 1, \ldots, n. \]
Let $\hat{k}_{ij} = k_{ij} \hat{x}_j$ and $\hat{k}_{ij} = -\sum_{j \neq i} \hat{k}_{ij}$. Then the number of Hamiltonian cycles $H_c$ is given by the relation [13]

$$
(3) \quad \left( \prod_{j=1}^{n} \hat{x}_j \right) H_c = \frac{1}{2} \hat{k}_{ij} \det \tilde{K}(i|i), \quad i = 1, \ldots, n.
$$

The task here is to express (3) in a form free of any $\hat{x}_i$, $i = 1, \ldots, n$. The result also leads to the resolution of enumeration of Hamiltonian paths in a graph.

It is well known that the enumeration of Hamiltonian cycles and paths in a complete graph $K_n$ and in a complete bipartite graph $K_{n_1n_2}$ can only be found from first combinatorial principles [7]. One wonders if there exists a formula which can be used very efficiently to produce $K_n$ and $K_{n_1n_2}$. Recently, using Lagrangian methods, Goulden and Jackson have shown that $H_c$ can be expressed in terms of the determinant and permanent of the adjacency matrix [5]. However, the formula of Goulden and Jackson determines neither $K_n$ nor $K_{n_1n_2}$ effectively. In this paper, using an algebraic method, we parametrize the adjacency matrix. The resulting formula also involves the determinant and permanent, but it can easily be applied to $K_n$ and $K_{n_1n_2}$. In addition, we eliminate the permanent from $H_c$ and show that $H_c$ can be represented by a determinantal function of multivariables, each variable with domain \{0, 1\}. Furthermore, we show that $H_c$ can be written by number of spanning trees of subgraphs. Finally, we apply the formulas to a complete multigraph $K_{n_1 \ldots n_p}$.

The conditions $a_{ij} = a_{ji}$, $i, j = 1, \ldots, n$, are not required in this paper. All formulas can be extended to a digraph simply by multiplying $H_c$ by 2. Some other discussion can be found in [4, 3].

3. Main theorem

\textbf{Notation.} For $p, q \in P$ and $n \in \omega$ we write $(q, n) \leq (p, n)$ if $q \leq p$ and $A_{q,n} = A_{p,n}$.

\begin{notation}
For $p, q \in P$ and $n \in \omega$
\end{notation}

\begin{proof}
Let $B = (b_{ij})$ be an $n \times n$ matrix. Let $n = \{1, \ldots, n\}$. Using the properties of (2), it is readily seen that

\textbf{Lemma 3.1.}

$$
(4) \quad \prod_{i \in n} \left( \sum_{j \in n} b_{ij} \hat{x}_j \right) = \left( \prod_{i \in n} \hat{x}_i \right) \text{per} B
$$

where \text{per} $B$ is the permanent of $B$.

\end{proof}
Let \( \hat{Y} = \{ \hat{y}_1, \ldots, \hat{y}_n \} \). Define multiplication for the elements of \( \hat{Y} \) by

\[
\hat{y}_i \hat{y}_j + \hat{y}_j \hat{y}_i = 0, \quad i, j = 1, \ldots, n.
\]

Then, it follows that

**Lemma 3.2.**

\[
\prod_{i \in n} \left( \sum_{j \in n} b_{ij} \hat{y}_j \right) = \left( \prod_{i \in n} \hat{y}_i \right) \det B.
\]

Note that all basic properties of determinants are direct consequences of Lemma 3.2. Write

\[
\sum_{j \in n} b_{ij} \hat{y}_j = \sum_{j \in n} b_{ij}^{(\lambda)} \hat{y}_j + (b_{ii} - \lambda_i) \hat{y}_i \hat{y}_i
\]

where

\[
b_{ii}^{(\lambda)} = \lambda_i, \quad b_{ij}^{(\lambda)} = b_{ij}, \quad i \neq j.
\]

Let \( B^{(\lambda)} = (b_{ij}^{(\lambda)}) \). By (6) and (7), it is straightforward to show the following result:

**Theorem 3.3.**

\[
\det B = \sum_{l=0}^{n} \sum_{I_l \subseteq n} \prod_{i \in I_l} (b_{ii} - \lambda_i) \det B^{(\lambda)}(I_l|I_l),
\]

where \( I_l = \{ i_1, \ldots, i_l \} \) and \( B^{(\lambda)}(I_l|I_l) \) is the principal submatrix (obtained from \( B^{(\lambda)} \) by deleting its \( i_1, \ldots, i_l \) rows and columns).

**Remark 3.1 (convention).** Let \( M \) be an \( n \times n \) matrix. The convention \( M(n|n) = 1 \) has been used in (9) and hereafter.

Before proceeding with our discussion, we pause to note that Theorem 3.3 yields immediately a fundamental formula which can be used to compute the coefficients of a characteristic polynomial [14]:

**Corollary 3.4.** Write \( \det(B - xI) = \sum_{l=0}^{n} (-1)^l b_l x^l \). Then

\[
b_l = \sum_{I_l \subseteq n} \det B(I_l|I_l).
\]

Let

\[
K(t, t_1, \ldots, t_n) = \begin{pmatrix}
D_1 t & -a_{12} t_2 & \cdots & -a_{1n} t_n \\
-a_{21} t_1 & D_2 t & \cdots & -a_{2n} t_n \\
\cdots & \cdots & \cdots & \cdots \\
-a_{n1} t_1 & -a_{n2} t_2 & \cdots & D_n t
\end{pmatrix},
\]

Proof: page numbers may be temporary
\begin{pmatrix} D_1t & -a_{12}t & \ldots & -a_{1n}t \\
-a_{21}t_1 & D_2t & \ldots & -a_{2n}t \\
\vdots & \ddots & \ddots & \vdots \\
-a_{n1}t_1 & -a_{n2}t_2 & \ldots & D_nt \end{pmatrix}

where

\[(12) \quad D_i = \sum_{j \in n} a_{ij}t_j, \quad i = 1, \ldots, n.\]

Set

\[D(t_1, \ldots, t_n) = \frac{\delta}{\delta t} \det K(t, t_1, \ldots, t_n)|_{t=1}.\]

Then

\[(13) \quad D(t_1, \ldots, t_n) = \sum_{i \in n} D_i \det K(t, t_1, \ldots, t_n; i|i),\]

where \(K(t = 1, t_1, \ldots, t_n; i|i)\) is the \(i\)th principal submatrix of \(K(t = 1, t_1, \ldots, t_n)\).

Theorem 3.3 leads to

\[(14) \quad \det K(t, t_1, \ldots, t_n) = \sum_{l \in n} (-1)^{|l|} t^{n-|l|} \prod_{i \in l} t_i \prod_{j \in l} (D_j + \lambda_j t_j) \det A^{(\lambda)}(T|T).\]

Note that

\[(15) \quad \det K(t = 1, t_1, \ldots, t_n) = \sum_{l \in n} (-1)^{|l|} \prod_{i \in l} t_i \prod_{j \in l} (D_j + \lambda_j t_j) \det A^{(\lambda)}(T|T) = 0.\]

Let \(t_i = \hat x_i, i = 1, \ldots, n.\) Lemma 3.1 yields

\[(16) \quad \biggl(\sum_{i \in n} a_{l_i}x_i\biggr) \det K(t = 1, x_1, \ldots, x_n; l|l) = \biggl(\prod_{i \in n} \hat x_i\biggr) \sum_{I \subseteq n - \{l\}} (-1)^{|I|} \per A^{(\lambda)}(I|I) \det A^{(\lambda)}(\overline{I \cup \{l\}}|\overline{I \cup \{l\}}).\]

By (3), (6), and (7), we have

Proof: page numbers may be temporary
Proposition 3.5.

\[ H_c = \frac{1}{2n} \sum_{l=0}^{n} (-1)^l D_l, \]

where

\[ D_l = \sum_{l_i \leq n} D(t_1, \ldots, t_n) 2^{l_i} \begin{cases} 0, & \text{if } i \in l_i \\ 1, & \text{otherwise} \end{cases} i=1,\ldots,n. \]

4. Application

We consider here the applications of Theorems 5.1 and 5.2 to a complete multipartite graph \( K_{n_1 \ldots n_p} \). It can be shown that the number of spanning trees of \( K_{n_1 \ldots n_p} \) may be written

\[ T = n^{p-2} \prod_{i=1}^{p} (n - n_i)^{n_i-1} \]

where

\[ n = n_1 + \cdots + n_p. \]

It follows from Theorems 5.1 and 5.2 that

\[ H_c = \frac{1}{2n} \sum_{l=0}^{n} (-1)^l (n - l)^{p-2} \sum_{l_1+\cdots+l_p=l} \prod_{i=1}^{p} \binom{n_i}{l_i} \cdot [(n - l) - (n_i - l_i)]^{n_i-l_i} \cdot [(n - l)^2 - \sum_{j=1}^{p} (n_i - l_i)^2]. \]

The enumeration of \( H_c \) in a \( K_{n_1 \ldots n_p} \) graph can also be carried out by Theorem 7.2 or 7.3 together with the algebraic method of (2). Some elegant representations may be obtained. For example, \( H_c \) in a \( K_{n_1 n_2 n_3} \) graph may be written

\[ H_c = \frac{n_1! \cdot n_2! \cdot n_3!}{n_1 + n_2 + n_3} \sum_{i} \left[ \binom{n_1}{i} \binom{n_2}{n_3 - n_1 + i} \binom{n_3}{n_3 - n_2 + i} \right. \]

\[ + \binom{n_1 - 1}{i} \binom{n_2 - 1}{n_3 - n_1 + i} \binom{n_3 - 1}{n_3 - n_2 + i}. \]

Proof: page numbers may be temporary.
5. Secret key exchanges

Modern cryptography is fundamentally concerned with the problem of secure private communication. A Secret Key Exchange is a protocol where Alice and Bob, having no secret information in common to start, are able to agree on a common secret key, conversing over a public channel. The notion of a Secret Key Exchange protocol was first introduced in the seminal paper of Diffie and Hellman [2]. [2] presented a concrete implementation of a Secret Key Exchange protocol, dependent on a specific assumption (a variant on the discrete log), specially tailored to yield Secret Key Exchange. Secret Key Exchange is of course trivial if trapdoor permutations exist. However, there is no known implementation based on a weaker general assumption.

The concept of an informationally one-way function was introduced in [8]. We give only an informal definition here:

**Definition 5.1 (one way).** A polynomial time computable function $f = \{f_k\}$ is informationally one-way if there is no probabilistic polynomial time algorithm which (with probability of the form $1 - k^{-e}$ for some $e > 0$) returns on input $y \in \{0, 1\}^k$ a random element of $f^{-1}(y)$.

In the non-uniform setting [8] show that these are not weaker than one-way functions:

**Theorem 5.1 ([8] (non-uniform)).** The existence of informationally one-way functions implies the existence of one-way functions.

We will stick to the convention introduced above of saying “non-uniform” before the theorem statement when the theorem makes use of non-uniformity. It should be understood that if nothing is said then the result holds for both the uniform and the non-uniform models.

It now follows from Theorem 5.1 that

**Theorem 5.2 (non-uniform).** Weak SKE implies the existence of a one-way function.

More recently, the polynomial-time, interior point algorithms for linear programming have been extended to the case of convex quadratic programs [19, 21], certain linear complementarity problems [11, 18], and the nonlinear complementarity problem [10]. The connection between these algorithms and the classical Newton method for nonlinear equations is well explained in [11].

6. Review

We begin our discussion with the following definition:

Proof: page numbers may be temporary
Definition 6.1. A function $H: \mathbb{R}^n \to \mathbb{R}^n$ is said to be $B$-differentiable at the point $z$ if (i) $H$ is Lipschitz continuous in a neighborhood of $z$, and (ii) there exists a positive homogeneous function $BH(z): \mathbb{R}^n \to \mathbb{R}^n$, called the $B$-derivative of $H$ at $z$, such that

$$\lim_{v \to 0} \frac{H(z + v) - H(z) - BH(z)v}{\|v\|} = 0.$$ 

The function $H$ is $B$-differentiable in set $S$ if it is $B$-differentiable at every point in $S$. The $B$-derivative $BH(z)$ is said to be strong if

$$\lim_{(v, v') \to (0, 0)} \frac{H(z + v) - H(z + v') - BH(z)(v - v')}{\|v - v'\|} = 0.$$ 

Lemma 6.1. There exists a smooth function $\psi_0(z)$ defined for $|z| > 1 - 2a$ satisfying the following properties:

(i) $\psi_0(z)$ is bounded above and below by positive constants $c_1 \leq \psi_0(z) \leq c_2$.

(ii) If $|z| > 1$, then $\psi_0(z) = 1$.

(iii) For all $z$ in the domain of $\psi_0$, $\Delta_0 \ln \psi_0 \geq 0$.

(iv) If $1 - 2a < |z| < 1 - a$, then $\Delta_0 \ln \psi_0 \geq c_3 > 0$.

Proof. We choose $\psi_0(z)$ to be a radial function depending only on $r = |z|$. Let $h(r) \geq 0$ be a suitable smooth function satisfying $h(r) \geq c_3$ for $1 - 2a < |z| < 1 - a$, and $h(r) = 0$ for $|z| > 1 - \frac{a}{2}$. The radial Laplacian

$$\Delta_0 \ln \psi_0(r) = \left(\frac{d^2}{dr^2} + \frac{1}{r} \frac{d}{dr}\right) \ln \psi_0(r)$$

has smooth coefficients for $r > 1 - 2a$. Therefore, we may apply the existence and uniqueness theory for ordinary differential equations. Simply let $\ln \psi_0(r)$ be the solution of the differential equation

$$\left(\frac{d^2}{dr^2} + \frac{1}{r} \frac{d}{dr}\right) \ln \psi_0(r) = h(r)$$

with initial conditions given by $\ln \psi_0(1) = 0$ and $\ln \psi_0'(1) = 0$.

Next, let $D_\nu$ be a finite collection of pairwise disjoint disks, all of which are contained in the unit disk centered at the origin in $C$. We assume that $D_\nu = \{z \mid |z - z_\nu| < \delta\}$. Suppose that $D_\nu(a)$ denotes the smaller concentric disk $D_\nu(a) = \{z \mid |z - z_\nu| \leq (1 - 2a)\delta\}$. We define a smooth weight function $\Phi_0(z)$ for $z \in C - \bigcup_\nu D_\nu(a)$ by setting $\Phi_0(z) = 1$ when $z \notin \bigcup_\nu D_\nu$ and $\Phi_0(z) = \psi_0((z - z_\nu)/\delta)$ when $z$ is an element of $D_\nu$. It follows from Lemma 6.1 that $\Phi_0$ satisfies the properties:

(i) $\Phi_0(z)$ is bounded above and below by positive constants $c_1 \leq \Phi_0(z) \leq c_2$.

(ii) $\Delta_0 \ln \Phi_0 \geq 0$ for all $z \in C - \bigcup_\nu D_\nu(a)$, the domain where the function $\Phi_0$ is defined.

Proof: page numbers may be temporary
(iii) \( \Delta_0 \ln \Phi_0 \geq c_3 \delta^{-2} \) when \((1 - 2a) \delta < |z - z_\nu| < (1 - a) \delta \).

Let \( A_\nu \) denote the annulus \( A_\nu = \{(1 - 2a) \delta < |z - z_\nu| < (1 - a) \delta \} \), and set \( A = \bigcup_\nu A_\nu \). The properties (2) and (3) of \( \Phi_0 \) may be summarized as
\[
\Delta_0 \ln \Phi_0 \geq c_3 \delta^{-2} \chi_A \text{, where } \chi_A \text{ is the characteristic function of } A. \]

Suppose that \( \alpha \) is a nonnegative real constant. We apply Proposition 3.5 with \( \Phi(z) = \Phi_0(z)e^{\alpha|z|^2} \). If \( u \in C_0^\infty(\mathbb{R}^2 - \bigcup_\nu D_\nu(a)) \), assume that \( D \) is a bounded domain containing the support of \( u \) and \( A \subset D \subset \mathbb{R}^2 - \bigcup_\nu D_\nu(a) \). A calculation gives
\[
\int_D \left| \bar{\partial}u \right|^2 \Phi_0(z)e^{\alpha|z|^2} \geq c_4 \alpha \int_D |u|^2 \Phi_0 e^{\alpha|z|^2} + c_5 \delta^{-2} \int_A |u|^2 \Phi_0 e^{\alpha|z|^2}.
\]

The boundedness, property (1) of \( \Phi_0 \), then yields
\[
\int_D \left| \bar{\partial}u \right|^2 e^{\alpha|z|^2} \geq c_6 \alpha \int_D |u|^2 e^{\alpha|z|^2} + c_7 \delta^{-2} \int_A |u|^2 e^{\alpha|z|^2}.
\]

Let \( B(X) \) be the set of blocks of \( \Lambda_X \) and let \( b(X) = |B(X)| \). If \( \phi \in Q_X \) then \( \phi \) is constant on the blocks of \( \Lambda_X \).

(24) \( P_X = \{ \phi \in M \mid \Lambda_\phi = \Lambda_X \} \), \( Q_X = \{ \phi \in M \mid \Lambda_\phi \supseteq \Lambda_X \} \).

If \( \Lambda_\phi \supseteq \Lambda_X \) then \( \Lambda_\phi = \Lambda_Y \) for some \( Y \geq X \) so that
\[
Q_X = \bigcup_{Y \geq X} P_Y.
\]

Thus by M"{o}bius inversion
\[
|P_Y| = \sum_{X \geq Y} \mu(Y, X) |Q_X|.
\]

Thus there is a bijection from \( Q_X \) to \( W^B(X) \). In particular \(|Q_X| = w^{b(X)}\).

Next note that \( b(X) = \dim X \). We see this by choosing a basis for \( X \) consisting of vectors \( v^k \) defined by
\[
v^k_i = \begin{cases} 
1 & \text{if } i \in \Lambda_k, \\
0 & \text{otherwise.}
\end{cases}
\]

\begin{cases} 
\{ & \text{if } i \in \Lambda_{\{k\}}, \\
0 & \text{otherwise.}
\end{cases}
\end{cases}
\]

<table>
<thead>
<tr>
<th>Lemma 6.2. Let ( A ) be an arrangement. Then</th>
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<td>( \chi(A, t) = \sum_{B \subseteq A} (-1)^{</td>
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Proof: page numbers may be temporary
In order to compute $R''$ recall the definition of $S(X, Y)$ from Lemma 3.1. Since $H \in B$, $A_H \subseteq B$. Thus if $T(B) = Y$ then $B \in S(H, Y)$. Let $L'' = L(A'')$.

Then

$$R'' = \sum_{H \in B \subseteq A} (-1)^{|B|} \ell^{|\dim T(B)|}$$

$$= \sum_{Y \in L''} \sum_{B \in S(H, Y)} (-1)^{|B|} \ell^{|\dim Y|}$$

$$= -\sum_{Y \in L''} \sum_{B \in S(H, Y)} (-1)^{|B - A_H|} \ell^{|\dim Y|}$$

$$= -\sum_{Y \in L''} \mu(H, Y) \ell^{|\dim Y|}$$

$$= -\chi(A'', t).$$

Corollary 6.3. Let $(A, A', A'')$ be a triple of arrangements. Then

$$\pi(A, t) = \pi(A', t) + t\pi(A'', t).$$

Definition 6.2. Let $(A, A', A'')$ be a triple with respect to the hyperplane $H \in A$. Call $H$ a separator if $T(A) \notin L(A')$.

Corollary 6.4. Let $(A, A', A'')$ be a triple with respect to $H \in A$.

(i) If $H$ is a separator then

$$\mu(A) = -\mu(A'')$$

and hence

$$|\mu(A)| = |\mu(A'')|.$$ (25)

(ii) If $H$ is not a separator then

$$\mu(A) = \mu(A') - \mu(A'')$$

and

$$|\mu(A)| = |\mu(A')| + |\mu(A'')|.$$ (26)

Proof. It follows from Theorem 5.1 that $\pi(A, t)$ has leading term

$$(-1)^{r(A)} \mu(A) t^{r(A)}.$$ (6)

The conclusion follows by comparing coefficients of the leading terms on both sides of the equation in Corollary 6.3. If $H$ is a separator then $r(A') < r(A)$ and there is no contribution from $\pi(A', t)$. $\square$

The Poincaré polynomial of an arrangement will appear repeatedly in these notes. It will be shown to equal the Poincaré polynomial of the graded algebras which we are going to associate with $A$. It is also the Poincaré polynomial of the complement $M(A)$ for a complex arrangement. Here we prove

Proof: page numbers may be temporary
Figure 1. \( Q(A_1) = xyz(x - z)(x + z)(y - z)(y + z) \)

Figure 2. \( Q(A_2) = xyz(x + y + z)(x + y - z)(x - y + z)(x - y - z) \)

that the Poincaré polynomial is the chamber counting function for a real arrangement. The complement \( M(A) \) is a disjoint union of chambers

\[
M(A) = \bigcup_{C \in \text{Cham}(A)} C.
\]

The number of chambers is determined by the Poincaré polynomial as follows.

**Theorem 6.5.** Let \( A_R \) be a real arrangement. Then

\[
|\text{Cham}(A_R)| = \pi(A_R, 1).
\]

**Proof.** We check the properties required in Corollary 6.4: (i) follows from \( \pi(\Phi_t, t) = 1 \), and (ii) is a consequence of Corollary 3.4. \( \square \)

**Theorem 6.6.** Let \( \phi \) be a protocol for a random pair \( (X, Y) \). If one of \( \sigma_\phi(x', y) \) and \( \sigma_\phi(x, y') \) is a prefix of the other and \( (x, y) \in S_{X,Y} \), then

\[
\langle \sigma_j(x', y) \rangle_{j=1}^\infty = \langle \sigma_j(x, y) \rangle_{j=1}^\infty = \langle \sigma_j(x, y') \rangle_{j=1}^\infty.
\]

**Proof:** page numbers may be temporary
Proof. We show by induction on $i$ that
\[
\langle \sigma_j(x', y) \rangle_{j=1}^i = \langle \sigma_j(x, y) \rangle_{j=1}^i = \langle \sigma_j(x, y') \rangle_{j=1}^i.
\]
The induction hypothesis holds vacuously for $i = 0$. Assume it holds for $i-1$, in particular $[\langle \sigma_j(x', y) \rangle_{j=1}^{i-1}] = [\langle \sigma_j(x, y') \rangle_{j=1}^{i-1}]$. Then one of $[\langle \sigma_j(x', y) \rangle_{j=1}^{i}]$ and $[\langle \sigma_j(x, y') \rangle_{j=1}^{i}]$ is a prefix of the other which implies that one of $\sigma_i(x', y)$ and $\sigma_i(x, y')$ is a prefix of the other. If the $i$th message is transmitted by $P_X$ then, by the separate-transmissions property and the induction hypothesis, $\sigma_i(x, y) = \sigma_i(x, y')$, hence one of $\sigma_i(x, y)$ and $\sigma_i(x', y)$ is a prefix of the other. By the implicit-termination property, neither $\sigma_i(x, y)$ nor $\sigma_i(x', y)$ can be a proper prefix of the other, hence they must be the same and $\sigma_i(x', y) = \sigma_i(x, y) = \sigma_i(x, y')$. If the $i$th message is transmitted by $P_Y$ then, symmetrically, $\sigma_i(x, y) = \sigma_i(x', y)$ by the induction hypothesis and the separate-transmissions property, and, then, $\sigma_i(x, y) = \sigma_i(x, y')$ by the implicit-termination property, proving the induction step. \hfill \Box

If $\phi$ is a protocol for $(X, Y)$, and $(x, y), (x', y)$ are distinct inputs in $S_{X,Y}$, then, by the correct-decision property, $[\langle \sigma_j(x, y) \rangle_{j=1}^\infty] \neq [\langle \sigma_j(x', y) \rangle_{j=1}^\infty]$.

Equation (25) defined $P_Y$'s ambiguity set $S_{X|Y}(y)$ to be the set of possible $X$ values when $Y = y$. The last corollary implies that for all $y \in S_Y$, the multiset\(^1\) of codewords $\{\sigma_\phi(x, y) : x \in S_{X|Y}(y)\}$ is prefix free.

7. One-way complexity

$\hat{C}_1(X|Y)$, the one-way complexity of a random pair $(X, Y)$, is the number of bits $P_X$ must transmit in the worst case when $P_Y$ is not permitted to transmit any feedback messages. Starting with $S_{X,Y}$, the support set of $(X, Y)$, we define $G(X|Y)$, the characteristic hypergraph of $(X, Y)$, and show that
\[
\hat{C}_1(X|Y) = \lceil \log \chi(G(X|Y)) \rceil.
\]

Let $(X, Y)$ be a random pair. For each $y$ in $S_Y$, the support set of $Y$, equation (25) defined $S_{X|Y}(y)$ to be the set of possible $x$ values when $Y = y$. The characteristic hypergraph $G(X|Y)$ of $(X, Y)$ has $S_X$ as its vertex set and the hyperedge $S_{X|Y}(y)$ for each $y \in S_Y$.

We can now prove a continuity theorem.

**Theorem 7.1.** Let $\Omega \subset \mathbb{R}^n$ be an open set, let $u \in BV(\Omega; \mathbb{R}^m)$, and let
\[
(26) \quad T_x^u = \left\{ y \in \mathbb{R}^m : y = \tilde{u}(x) + \left\langle \frac{Du}{|Du|}(x), z \right\rangle \text{ for some } z \in \mathbb{R}^n \right\}
\]

\(^1\)A multiset allows multiplicity of elements. Hence, \(\{0, 01, 01\}\) is prefix free as a set, but not as a multiset.

Proof: page numbers may be temporary
for every $x \in \Omega \setminus S_u$. Let $f : \mathbb{R}^m \to \mathbb{R}^k$ be a Lipschitz continuous function such that $f(0) = 0$, and let $v = f(u) : \Omega \to \mathbb{R}^k$. Then $v \in BV(\Omega; \mathbb{R}^k)$ and

$$Jv = (f(u^+) - f(u^-)) \otimes \nu_u \cdot \mathcal{H}_{n-1} \big| S_u.$$  

(27)

In addition, for $|\tilde{D}u|$-almost every $x \in \Omega$ the restriction of the function $f$ to $T_x^u$ is differentiable at $\tilde{u}(x)$ and

$$\tilde{D}v = \nabla (f|_{T_x^u})(\tilde{u}) \frac{\tilde{D}u}{|\tilde{D}u|} \cdot |\tilde{D}u|.$$  

(28)

Before proving the theorem, we state without proof three elementary remarks which will be useful in the sequel.

**Remark 7.1.** Let $\omega : ]0, +\infty[ \to ]0, +\infty[ $ be a continuous function such that $\omega(t) \to 0$ as $t \to 0$. Then

$$\lim_{h \to 0^+} g(\omega(h)) = L \iff \lim_{h \to 0^+} g(h) = L$$

for any function $g : ]0, +\infty[ \to \mathbb{R}$.

**Remark 7.2.** Let $g : \mathbb{R}^n \to \mathbb{R}$ be a Lipschitz continuous function and assume that

$$L(z) = \lim_{h \to 0^+} \frac{g(hz) - g(0)}{h}$$

exists for every $z \in \mathbb{Q}^n$ and that $L$ is a linear function of $z$. Then $g$ is differentiable at 0.

**Remark 7.3.** Let $A : \mathbb{R}^n \to \mathbb{R}^m$ be a linear function, and let $f : \mathbb{R}^m \to \mathbb{R}$ be a function. Then the restriction of $f$ to the range of $A$ is differentiable at 0 if and only if $f(A) : \mathbb{R}^n \to \mathbb{R}$ is differentiable at 0 and

$$\nabla (f|_{\text{Im}(A)})(0) A = \nabla (f(A))(0).$$

**Proof.** We begin by showing that $v \in BV(\Omega; \mathbb{R}^k)$ and

$$|Dv| (B) \leq K |Du| (B) \quad \forall B \in \mathcal{B}(\Omega),$$

(29)

where $K > 0$ is the Lipschitz constant of $f$. By (13) and by the approximation result quoted in §3, it is possible to find a sequence $(u_h) \subset C^1(\Omega; \mathbb{R}^m)$ converging to $u$ in $L^1(\Omega; \mathbb{R}^m)$ and such that

$$\lim_{h \to +\infty} \int_{\Omega} |\nabla u_h| \, dx = |Du| (\Omega).$$

The functions $v_h = f(u_h)$ are locally Lipschitz continuous in $\Omega$, and the definition of differential implies that $|\nabla v_h| \leq K |\nabla u_h|$ almost everywhere in $\Omega$. The
lower semicontinuity of the total variation and (13) yield

\[ |Dv|(\Omega) \leq \liminf_{h \to +\infty} |Dv_h|(\Omega) = \liminf_{h \to +\infty} \int_\Omega |\nabla v_h| \, dx \]

\[ \leq K \liminf_{h \to +\infty} \int_\Omega |\nabla u_h| \, dx = K |Du|(\Omega). \]

(30)

Since \( f(0) = 0 \), we have also

\[ \int_\Omega |v| \, dx \leq K \int_\Omega |u| \, dx; \]

therefore \( u \in BV(\Omega; \mathbb{R}^k) \). Repeating the same argument for every open set \( A \subset \Omega \), we get (29) for every \( B \in \mathcal{B}(\Omega) \), because \( |Dv|, |Du| \) are Radon measures. To prove Lemma 6.1, first we observe that

\[ S_v \subset S_u, \quad \tilde{v}(x) = f(\tilde{u}(x)) \quad \forall x \in \Omega \setminus S_u. \]

(31)

In fact, for every \( \varepsilon > 0 \) we have

\[ \{ y \in B_\rho(x) : |v(y) - f(\tilde{u}(x))| > \varepsilon \} \subset \{ y \in B_\rho(x) : |u(y) - \tilde{u}(x)| > \varepsilon/K \}, \]

hence

\[ \lim_{\rho \to 0^+} \frac{\{ y \in B_\rho(x) : |v(y) - f(\tilde{u}(x))| > \varepsilon \}}{\rho^n} = 0 \]

whenever \( x \in \Omega \setminus S_u \). By a similar argument, if \( x \in S_u \) is a point such that there exists a triplet \((u^+, u^-, \nu_u)\) satisfying (14), (15), then

\[ (v^+(x) - v^-(x)) \otimes \nu_v = (f(u^+(x)) - f(u^-(x))) \otimes \nu_u \quad \text{if} \ x \in S_v \]

and \( f(u^-(x)) = f(u^+(x)) \) if \( x \in S_u \setminus S_v \). Hence, by (1.8) we get

\[ Jv(B) = \int_{B \setminus S_v} (v^+ - v^-) \otimes \nu_v \, dH_{n-1} = \int_{B \setminus S_u} (f(u^+) - f(u^-)) \otimes \nu_u \, dH_{n-1} \]

\[ = \int_{B \setminus S_u} (f(u^+) - f(u^-)) \otimes \nu_u \, dH_{n-1} \]

and Lemma 6.1 is proved. \( \Box \)

To prove (31), it is not restrictive to assume that \( k = 1 \). Moreover, to simplify our notation, from now on we shall assume that \( \Omega = \mathbb{R}^n \). The proof of (31) is divided into two steps. In the first step we prove the statement in the one-dimensional case \( (n = 1) \), using Theorem 5.2. In the second step we achieve the general result using Theorem 7.1.

Step 1. Assume that \( n = 1 \). Since \( S_u \) is at most countable, (7) yields that \( |\bar{D}v| (S_u \setminus S_v) = 0 \), so that (19) and (21) imply that \( Dv \equiv \bar{D}v + Jv \) is the
Radon-Nikodým decomposition of $Dv$ in absolutely continuous and singular part with respect to $|Du|$. By Theorem 5.2, we have

\[
\frac{\tilde{D}v}{|Du|}(t) = \lim_{s \to t^+} \frac{Dv([t,s])}{|Du|(t,s)}, \quad \frac{\tilde{D}u}{|Du|}(t) = \lim_{s \to t^+} \frac{Du([t,s])}{|Du|(t,s)}
\]

$|Du|$-almost everywhere in $\mathbb{R}$. It is well known (see, for instance, [20, 2.5.16]) that every one-dimensional function of bounded variation $w$ has a unique left continuous representative, i.e., a function $\hat{w}$ such that $\hat{w} = w$ almost everywhere and $\lim_{s \to t^-} \hat{w}(s) = \hat{w}(t)$ for every $t \in \mathbb{R}$. These conditions imply

\[
(32) \quad \hat{u}(t) = Du([-\infty,t]), \quad \hat{v}(t) = Dv([-\infty,t]) \quad \forall t \in \mathbb{R}
\]

and

\[
(33) \quad \hat{v}(t) = f(\hat{u}(t)) \quad \forall t \in \mathbb{R}.
\]

Let $t \in \mathbb{R}$ be such that $|\tilde{D}u|([t,s]) > 0$ for every $s > t$ and assume that the limits in (22) exist. By (23) and (24) we get

\[
\hat{v}(s) - \hat{v}(t) = \frac{f(\hat{u}(s)) - f(\hat{u}(t))}{|\tilde{D}u|([t,s])}
\]

\[
= \frac{f(\hat{u}(s)) - f(\hat{u}(t)) + \frac{\tilde{D}u}{|Du|}(t)|\tilde{D}u|([t,s])}{|\tilde{D}u|([t,s])}
\]

\[
= \frac{f(\hat{u}(t)) + \frac{\tilde{D}u}{|Du|}(t)|\tilde{D}u|([t,s]) - f(\hat{u}(t))}{\tilde{D}u|([t,s])} + \frac{\tilde{D}u}{|Du|}(t)|\tilde{D}u|([t,s])
\]

for every $s > t$. Using the Lipschitz condition on $f$ we find

\[
\left| \frac{\hat{v}(s) - \hat{v}(t)}{|\tilde{D}u|([t,s])} \right| \leq K \left| \frac{\hat{u}(s) - \hat{u}(t)}{|\tilde{D}u|([t,s])} + \frac{\tilde{D}u}{|Du|}(t) \right|
\]

Proof: page numbers may be temporary
By \((29)\), the function \(s \rightarrow |\tilde{D}u|(t, s)\) is continuous and converges to 0 as \(s \downarrow t\).

Therefore Remark 7.1 and the previous inequality imply

\[
\frac{\tilde{D}v}{|\tilde{D}u|}(t) = \lim_{h \to 0^+} \frac{f(\tilde{u}(t) + h \frac{\tilde{D}u}{|\tilde{D}u|}(t)) - f(\tilde{u}(t))}{h} \quad |\tilde{D}u|\text{-a.e. in } \mathbb{R}.
\]

By \((22)\), \(\tilde{u}(x) = \tilde{u}(x)\) for every \(x \in \mathbb{R}\setminus S_u\); moreover, applying the same argument to the functions \(u'(t) = u(-t), v'(t) = f(u'(t)) = v(-t)\), we get

\[
\frac{\tilde{D}v}{|\tilde{D}u|}(t) = \lim_{h \to 0} \frac{f(\tilde{u}(t) + h \frac{\tilde{D}u}{|\tilde{D}u|}(t)) - f(\tilde{u}(t))}{h} \quad |\tilde{D}u|\text{-a.e. in } \mathbb{R}
\]

and our statement is proved.

**Step 2.** Let us consider now the general case \(n > 1\). Let \(\nu \in \mathbb{R}^n\) be such that \(|\nu| = 1\), and let \(\pi_\nu = \{y \in \mathbb{R}^n : \langle y, \nu \rangle = 0\}\). In the following, we shall identify \(\mathbb{R}^n\) with \(\pi_\nu \times \mathbb{R}\), and we shall denote by \(y\) the variable ranging in \(\pi_\nu\) and by \(t\) the variable ranging in \(\mathbb{R}\). By the just proven one-dimensional result, and by Theorem 3.3, we get

\[
\lim_{h \to 0} \frac{f(\tilde{u}(y + t\nu) + h \frac{\tilde{D}u_y}{|\tilde{D}u_y|}(t)) - f(\tilde{u}(y + t\nu))}{h} = \frac{\tilde{D}v_y}{|\tilde{D}u_y|}(t) \quad |\tilde{D}u_y|\text{-a.e. in } \mathbb{R}
\]

for \(\mathcal{H}_{n-1}\)-almost every \(y \in \pi_\nu\). We claim that

\[
\langle \frac{\tilde{D}u_y}{|\tilde{D}u_y|}, \nu \rangle \frac{\tilde{D}u_y}{|\tilde{D}u_y|}(y + t\nu) = \frac{\tilde{D}u_y}{|\tilde{D}u_y|}(t) \quad |\tilde{D}u_y|\text{-a.e. in } \mathbb{R}
\]

for \(\mathcal{H}_{n-1}\)-almost every \(y \in \pi_\nu\). In fact, by \((16)\) and \((18)\) we get

\[
\int_{\pi_\nu} \frac{\tilde{D}u_y}{|\tilde{D}u_y|} \cdot |\tilde{D}u_y| \, d\mathcal{H}_{n-1}(y) = \int_{\pi_\nu} \tilde{D}u_y \, d\mathcal{H}_{n-1}(y)
\]

\[
= \langle \tilde{D}u, \nu \rangle \frac{\tilde{D}u}{|\tilde{D}u|} \cdot |\tilde{D}u| = \int_{\pi_\nu} \frac{\tilde{D}u_y}{|\tilde{D}u_y|}(y + t\nu) \cdot |\tilde{D}u_y| \, d\mathcal{H}_{n-1}(y)
\]

and \((24)\) follows from \((13)\). By the same argument it is possible to prove that

\[
\langle \frac{\tilde{D}v_y}{|\tilde{D}u_y|}, \nu \rangle \frac{\tilde{D}v_y}{|\tilde{D}u_y|}(y + t\nu) = \frac{\tilde{D}v_y}{|\tilde{D}u_y|}(t) \quad |\tilde{D}u_y|\text{-a.e. in } \mathbb{R}
\]

Proof: page numbers may be temporary
for $\mathcal{H}_{n-1}$-almost every $y \in \pi_\nu$. By (24) and (25) we get
\[
\lim_{h \to 0} \frac{f(\tilde{u}(y + t\nu) + h \langle \tilde{D}u, \nu \rangle (y + t\nu)) - f(\tilde{u}(y + t\nu))}{h} = \frac{\langle \tilde{D}v, \nu \rangle}{\langle \tilde{D}u, \nu \rangle} (y + t\nu)
\]
for $\mathcal{H}_{n-1}$-almost every $y \in \pi_\nu$, and using again (14), (15) we get
\[
\lim_{h \to 0} \frac{f(\tilde{u}(x) + h \frac{\langle \tilde{D}u, \nu \rangle}{\langle \tilde{D}u, \nu \rangle} (x)) - f(\tilde{u}(x))}{h} = \frac{\langle \tilde{D}v, \nu \rangle}{\langle \tilde{D}u, \nu \rangle} (x)
\]
for $\mathcal{H}_{n-1}$-almost every $y \in \pi_\nu$, and using again (14), (15) we get
\[
\lim_{h \to 0} \frac{f(\tilde{u}(x) + h \frac{\langle \tilde{D}u, \nu \rangle}{\langle \tilde{D}u, \nu \rangle} (x)) - f(\tilde{u}(x))}{h} = \frac{\langle \tilde{D}v, \nu \rangle}{\langle \tilde{D}u, \nu \rangle} (x)
\]
\[
\frac{\langle \tilde{D}u, \nu \rangle}{\langle \tilde{D}u, \nu \rangle} \text{-a.e. in } \mathbb{R}^n.
\]
Since the function $\frac{\langle \tilde{D}u, \nu \rangle}{\tilde{D}u}$ is strictly positive $\langle \tilde{D}u, \nu \rangle$-almost everywhere, we obtain also
\[
\lim_{h \to 0} \frac{f(\tilde{u}(x) + h \frac{\langle \tilde{D}u, \nu \rangle}{\langle \tilde{D}u, \nu \rangle} (x)) - f(\tilde{u}(x))}{h} = \frac{\langle \tilde{D}v, \nu \rangle}{\langle \tilde{D}u, \nu \rangle} (x)
\]
\[
\langle \tilde{D}u, \nu \rangle \text{-almost everywhere in } \mathbb{R}^n.
\]
Finally, since
\[
\frac{\langle \tilde{D}u, \nu \rangle}{\tilde{D}u} \frac{\langle \tilde{D}u, \nu \rangle}{\langle \tilde{D}u, \nu \rangle} = \frac{\langle \tilde{D}u, \nu \rangle}{\tilde{D}u} = \frac{\tilde{D}u}{\tilde{D}u}, \nu \rangle \text{ a.e. in } \mathbb{R}^n
\]
\[
\frac{\langle \tilde{D}u, \nu \rangle}{\tilde{D}u} \frac{\langle \tilde{D}v, \nu \rangle}{\langle \tilde{D}u, \nu \rangle} = \frac{\langle \tilde{D}v, \nu \rangle}{\tilde{D}u} = \frac{\tilde{D}v}{\tilde{D}u}, \nu \rangle \text{ a.e. in } \mathbb{R}^n
\]
and since both sides of (33) are zero $\tilde{D}u$-almost everywhere on $\langle \tilde{D}u, \nu \rangle$-negligible sets, we conclude that
\[
\lim_{h \to 0} \frac{f \left( \tilde{u}(x) + h \frac{\langle \tilde{D}u, \nu \rangle}{\langle \tilde{D}u, \nu \rangle} (x), \nu \right) \right) - f(\tilde{u}(x))}{h} = \frac{\tilde{D}v}{\tilde{D}u} (x), \nu \rangle ,
\]
$\tilde{D}u$-a.e. in $\mathbb{R}^n$. Since $\nu$ is arbitrary, by Remarks 7.2 and 7.3 the restriction of $f$ to the affine space $T_x^\nu$ is differentiable at $\tilde{u}(x)$ for $\tilde{D}u$-almost every $x \in \mathbb{R}^n$ and (26) holds.
\[\square\]
It follows from (13), (14), and (15) that
\[ D(t_1, \ldots, t_n) = \sum_{I \in \mathcal{P}_n} (-1)^{|I|-1} |I| \prod_{i \in I} t_i \prod_{j \in I} (D_j + \lambda_j t_j) \det A(\lambda)(T|I). \]

Let \( t_i = \hat{x}_i, i = 1, \ldots, n. \) Lemma 1 leads to
\[ D(\hat{x}_1, \ldots, \hat{x}_n) = \prod_{i \in n} \hat{x}_i \sum_{I \in \mathcal{P}_n} (-1)^{|I|-1} |I| \per A(\lambda)(I|I) \det A(\lambda)(T|I). \]

By (3), (13), and (37), we have the following result:

**Theorem 7.2.**
\[ H_c = \frac{1}{2n} \sum_{l=1}^{n-l} (-1)^{l-1} A_l^{(\lambda)}, \]
where
\[ A_l^{(\lambda)} = \sum_{I \subseteq \mathcal{P}_n} \per A(\lambda)(I|I) \det A(\lambda)(I|I), |I| = l. \]

It is worth noting that \( A_l^{(\lambda)} \) of (39) is similar to the coefficients \( b_l \) of the characteristic polynomial of (10). It is well known in graph theory that the coefficients \( b_l \) can be expressed as a sum over certain subgraphs. It is interesting to see whether \( A_l, \lambda = 0, \) structural properties of a graph.

We may call (38) a parametric representation of \( H_c. \) In computation, the parameter \( \lambda_i \) plays very important roles. The choice of the parameter usually depends on the properties of the given graph. For a complete graph \( K_n, \) let \( \lambda_i = 1, i = 1, \ldots, n. \) It follows from (39) that
\[ A_l^{(1)} = \begin{cases} n!, & \text{if } l = 1 \\ 0, & \text{otherwise.} \end{cases} \]

By (38)
\[ H_c = \frac{1}{2} (n-1)!. \]

For a complete bipartite graph \( K_{n_1n_2}, \) let \( \lambda_i = 0, i = 1, \ldots, n. \) By (39),
\[ A_l = \begin{cases} -n_1!n_2! \delta_{n_1n_2}, & \text{if } l = 2 \\ 0, & \text{otherwise.} \end{cases} \]

Theorem 7.2 leads to
\[ H_c = \frac{1}{n_1 + n_2} n_1!n_2! \delta_{n_1n_2}. \]
Now, we consider an asymmetrical approach. Theorem 3.3 leads to

\[
(44) \quad \det K(t = 1, t_1, \ldots, t_n; l | l) = \sum_{I \subseteq \mathbb{N} - \{l\}} (-1)^{|I|} \prod_{i \in I} t_i \prod_{j \in I} (D_j + \lambda_j t_j) \det A^{(\lambda)}(T \cup \{l\})T \cup \{l\}).
\]

By (3) and (16) we have the following asymmetrical result:

**Theorem 7.3.**

\[
(45) \quad H_c = \frac{1}{2} \sum_{I \subseteq \mathbb{N} - \{l\}} (-1)^{|I|} \text{perm} A^{(\lambda)}(I | I) \det A^{(\lambda)}(I \cup \{l\})I \cup \{l\})
\]

which reduces to Goulden–Jackson’s formula when \(\lambda_i = 0, i = 1, \ldots, n\) [14].

8. Various font features of the amsmath package

8.1. **Bold versions of special symbols.** In the amsmath package \texttt{\textbackslash boldsymbol} is used for getting individual bold math symbols and bold Greek letters—everything in math except for letters of the Latin alphabet, where you’d use \texttt{\textbackslash mathbf}. For example,

\[
A_\infty + \pi A_0 \sim A_\infty + \pi A_0
\]

8.2. “Poor man’s bold”. If a bold version of a particular symbol doesn’t exist in the available fonts, then \texttt{\textbackslash boldsymbol} can’t be used to make that symbol bold. At the present time, this means that \texttt{\textbackslash boldsymbol} can’t be used with symbols from the \texttt{msam} and \texttt{msbm} fonts, among others. In some cases, poor man’s bold (\texttt{\textbackslash pmb}) can be used instead of \texttt{\textbackslash boldsymbol}:

\[
\frac{\partial x}{\partial y} \bigg| \frac{\partial y}{\partial z}
\]

\[
\frac{\partial x}{\partial y} \bigg| \frac{\partial y}{\partial z}
\]

So-called “large operator” symbols such as \(\sum\) and \(\prod\) require an additional command, \texttt{\textbackslash mathop}, to produce proper spacing and limits when \texttt{\textbackslash pmb} is used. For further details see The \(\text{T}_{\text{ET}}\text{X}\)book.

\[
\sum_{i < B} \prod_{i \text{ odd}} \kappa F(r_i) \quad \sum_{i < B} \prod_{i \text{ odd}} \kappa(r_i)
\]
AMS and BORIS VEYTSMAN

\[
\sum_{\substack{i<B \\	ext{$i$ odd}}} \prod_\kappa \kappa F(r_i) \qquad \mathop\pmb{\sum}_{\substack{i<B \\	ext{$i$ odd}}} \mathop\pmb{\prod}_\kappa \kappa(r_i)
\]

9. Compound symbols and other features

9.1. Multiple integral signs. \iint, \iiint, \iiiint give multiple integral signs with the spacing between them nicely adjusted, in both text and display style. \idotsint gives two integral signs with dots between them.

\[ \iint_A f(x,y) \, dx \, dy \quad \iiint_A f(x,y,z) \, dx \, dy \, dz \]

\[ \iiiint_A f(w,x,y,z) \, dw \, dx \, dy \, dz \]

9.2. Over and under arrows. Some extra over and under arrow operations are provided in the amsmath package. (Basic \LaTeX{} provides \overrightarrow and \overleftarrow).

\begin{align*}
\psi_\delta(t) E_t h &= \overrightarrow{\psi_\delta(t) E_t h} \\
\psi_\delta(t) E_t h &= \underleftarrow{\psi_\delta(t) E_t h} \\
\psi_\delta(t) E_t h &= \overleftrightarrow{\psi_\delta(t) E_t h}
\end{align*}

These all scale properly in subscript sizes:

\[
\int_{\overrightarrow{AB}} ax \, dx
\]

9.3. Dots. Normally you need only type \dots for ellipsis dots in a math formula. The main exception is when the dots fall at the end of the formula; then you need to specify one of \dotsc (series dots, after a comma), \dotsb

Proof: page numbers may be temporary
(binary dots, for binary relations or operators), $\texttt{\textbackslash dotsm}$ (multiplication dots), or $\texttt{\textbackslash dotsi}$ (dots after an integral). For example, the input

Then we have the series $A_1,A_2,\ldots$, the regional sum $A_1+A_2+\ldots$, the orthogonal product $A_1A_2\ldots$, and the infinite integral

\[ \int_{A_1} \int_{A_2} \cdots \]

produces

Then we have the series $A_1,A_2,\ldots$, the regional sum $A_1+A_2+\cdots$, the orthogonal product $A_1A_2\cdots$, and the infinite integral

\[ \int_{A_1} \int_{A_2} \cdots \]

9.4. Accents in math. Double accents:

\[
\hat{H} \quad \check{C} \quad \tilde{T} \quad \acute{A} \quad \grave{G} \quad \dot{D} \quad \ddot{D} \quad \breve{B} \quad \bar{B} \quad \vec{V}
\]

This double accent operation is complicated and tends to slow down the processing of a LaTeX file.

9.5. Dot accents. $\texttt{\textbackslash ddot}$ and $\texttt{\textbackslash dddot}$ are available to produce triple and quadruple dot accents in addition to the $\texttt{\textbackslash dot}$ and $\texttt{\textbackslash ddot}$ accents already available in LaTeX:

\[
\dddot{Q} \qquad \ddddot{R}
\]

9.6. Roots. In the amsmath package $\texttt{\leftroot}$ and $\texttt{\uproot}$ allow you to adjust the position of the root index of a radical:

\[
\sqrt[\leftroot{-2}\uproot{2}\beta]{k}
\]

gives good positioning of the $\beta$:

\[
\sqrt[\beta]{k}
\]

9.7. Boxed formulas. The command $\texttt{\boxed}$ puts a box around its argument, like $\texttt{\fbox}$ except that the contents are in math mode:

\[
\boxed{W_t-F \subseteq V(P_i) \subseteq W_t}
\]

Proof: page numbers may be temporary
9.8. Extensible arrows. $\xleftarrow{}$ and $\xrightarrow{}$ produce arrows that extend automatically to accommodate unusually wide subscripts or superscripts. The text of the subscript or superscript are given as an optional resp. mandatory argument: Example:

$$0 \xleftarrow{\zeta} F \times \triangle [n-1] \xrightarrow{\partial_0 \alpha (b)} E^{\partial_0 b}$$

9.9. $\overset{\text{\text}, \underset{\text}, \sideset{\text}{}{\text}}{\text}$. Examples:

$$\overset{*}{X} \quad \underset{*}{X} \quad \overset{a}{\underset{b}{X}}$$

The command $\sideset{\text}{}{\text}$ is for a rather special purpose: putting symbols at the subscript and superscript corners of a large operator symbol such as $\sum$ or $\prod$, without affecting the placement of limits. Examples:

$$\sideset{*}{*}{\prod}_k \qquad \sideset{}{'}{\sum}_{0 \leq i \leq m} E_i \beta x$$

9.10. The $\text$ command. The main use of the command $\text$ is for words or phrases in a display:

$$y = y' \quad \text{if and only if} \quad y'_k = \delta_k y_{\tau(k)}$$

9.11. Operator names. The more common math functions such as log, sin, and lim have predefined control sequences: $\log$, $\sin$, $\lim$. The amsmath package provides $\DeclareMathOperator{}$ and $\DeclareMathOperator*{}$ for producing new function names that will have the same typographical treatment. Examples:

$$\|f\|_\infty = \esssup_{x \in \mathbb{R}^n} |f(x)|$$

Proof: page numbers may be temporary
\[ \{ u \in \mathbb{R}^+ \colon f^*(u) > \alpha \} = \{ x \in \mathbb{R}^n \colon |f(x)| \geq \alpha \} \quad \forall \alpha > 0. \]

\[ \text{esssup} \quad \text{and} \quad \text{meas} \quad \text{would be defined in the document preamble as} \]

\[ \text{\texttt{\MakeTextUppercase{\textbackslash DeclareMathOperator*{\textbackslash esssup}{ess\textbackslash s\textbackslash up}}}} \quad \text{\texttt{\MakeTextUppercase{\textbackslash DeclareMathOperator{\textbackslash meas}{meas}}}} \]

The following special operator names are predefined in the \texttt{amsmath} package: \texttt{\textbackslash varlimsup}, \texttt{\textbackslash varliminf}, \texttt{\textbackslash varinjlim}, and \texttt{\textbackslash varprojlim}. Here’s what they look like in use:

\begin{align}
& \varlimsup_{n \to \infty} Q(u_n, u_n - u^\#) \leq 0 \\
& \varliminf_{n \to \infty} \left| a_{n+1} \right| / \left| a_n \right| = 0 \\
& \varinjlim (m_i^\lambda \cdot)^* \leq 0 \\
& \varprojlim_{p \in S(A)} A_p \leq 0
\end{align}

9.12. \texttt{\textbackslash mod} and its relatives. The commands \texttt{\textbackslash mod} and \texttt{\textbackslash pod} are variants of \texttt{\textbackslash pmod} preferred by some authors; \texttt{\textbackslash mod} omits the parentheses, whereas \texttt{\textbackslash pod} omits the ‘mod’ and retains the parentheses. Examples:

\begin{align}
& x \equiv y + 1 \pmod{m^2} \\
& x \equiv y + 1 \mod{m^2} \\
& x \equiv y + 1 \pod{m^2}
\end{align}

9.13. Fractions and related constructions. The usual notation for binomials is similar to the fraction concept, so it has a similar command \texttt{\textbackslash binom} with
two arguments. Example:
\[
\sum_{\gamma \in \Gamma_C} I_\gamma = 2^k - \binom{k}{1}2^{k-1} + \binom{k}{2}2^{k-2} \\
+ \cdots + (-1)^l \binom{k}{l}2^{k-l} + \cdots + (-1)^k \\
= (2 - 1)^k = 1
\]

There are also abbreviations
\begin{equation}
\begin{split}
\sum_{\gamma \in \Gamma_C} I_\gamma &= 2^k - \binom{k}{1}2^{k-1} + \binom{k}{2}2^{k-2} \\
&\quad + \cdots + (-1)^l \binom{k}{l}2^{k-l} + \cdots + (-1)^k \\
&= (2 - 1)^k = 1
\end{split}
\end{equation}

The generalized fraction command \texttt{\textbackslash genfrac} provides full access to the six \TeX{} fraction primitives:
\begin{align*}
\text{(56)} & \quad \text{\texttt{\textbackslash over}: } & \frac{n+1}{2} & \quad \text{\texttt{\textbackslash overwithdelims}: } \left( \begin{array}{c} n+1 \\ 2 \end{array} \right) \\
\text{(57)} & \quad \text{\texttt{\textbackslash atop}: } & \frac{n+1}{2} & \quad \text{\texttt{\textbackslash atopwithdelims}: } \left( \begin{array}{c} n+1 \\ 2 \end{array} \right) \\
\text{(58)} & \quad \text{\texttt{\textbackslash above}: } & \frac{n+1}{2} & \quad \text{\texttt{\textbackslash abovewithdelims}: } \left[ \begin{array}{c} n+1 \\ 2 \end{array} \right]
\end{align*}

\begin{verbatim}
\text{\texttt{\textbackslash over}: } & \genfrac{}{}{}{}{n+1}{2} & \text{\texttt{\textbackslash overwithdelims}: } & \left( \begin{array}{c} n+1 \\ 2 \end{array} \right) \\
\text{\texttt{\textbackslash atop}: } & \genfrac{}{}{0pt}{}{n+1}{2} & \text{\texttt{\textbackslash atopwithdelims}: } & \left( \begin{array}{c} n+1 \\ 2 \end{array} \right) \\
\text{\texttt{\textbackslash above}: } & \genfrac{}{}{1pt}{}{n+1}{2} & \text{\texttt{\textbackslash abovewithdelims}: } & \left[ \begin{array}{c} n+1 \\ 2 \end{array} \right]
\end{verbatim}

Proof: page numbers may be temporary
9.14. **Continued fractions.** The continued fraction

\[
\frac{1}{\sqrt{2} + \frac{1}{\sqrt{2} + \frac{1}{\sqrt{2} + \frac{1}{\sqrt{2} + \cdots}}}}
\]

can be obtained by typing

\[
\cfrac{1}{\sqrt{2} + \cfrac{1}{\sqrt{2} + \cfrac{1}{\sqrt{2} + \cfrac{1}{\sqrt{2} + \cdots}}}}
\]

Left or right placement of any of the numerators is accomplished by using \cfrac[l] or \cfrac[r] instead of \cfrac.

9.15. **Smash.** In amsmath there are optional arguments t and b for the plain \TeX{} command \smash, because sometimes it is advantageous to be able to ‘smash’ only the top or only the bottom of something while retaining the natural depth or height. In the formula \(X_j = (1/\sqrt{\lambda_j})X'_j\) \smash[b] has been used to limit the size of the radical symbol.

\[
X_j = (1/\sqrt{\smash[b]{\lambda_j}})X'_j
\]

Without the use of \smash[b] the formula would have appeared thus: \(X_j = (1/\sqrt{\lambda_j})X'_j\), with the radical extending to encompass the depth of the subscript \(j\).

9.16. **The ‘cases’ environment.** ‘Cases’ constructions like the following can be produced using the cases environment.

\[
P_{r-j} = \begin{cases}
0 & \text{if } r - j \text{ is odd}, \\
r!(-1)^{(r-j)/2} & \text{if } r - j \text{ is even}.
\end{cases}
\]

\[
\text{Proof: page numbers may be temporary}
\]
9.17. *Matrix.* Here are samples of the matrix environments, \( \text{\textbackslash{matrix}}, \text{\textbackslash{pmatrix}}, \text{\textbackslash{bmatrix}}, \text{\textbackslash{Bmatrix}}, \text{\textbackslash{vmatrix}} \text{and} \text{\textbackslash{Vmatrix}}: \\

\[
\begin{bmatrix}
\vartheta & \varrho \\
\varphi & \varpi
\end{bmatrix}
\begin{pmatrix}
\vartheta & \varrho \\
\varphi & \varpi
\end{pmatrix}
\begin{bmatrix}
\vartheta & \varrho \\
\varphi & \varpi
\end{bmatrix}
\begin{Bmatrix}
\vartheta & \varrho \\
\varphi & \varpi
\end{Bmatrix}
\begin{vmatrix}
\vartheta & \varrho \\
\varphi & \varpi
\end{vmatrix}
\begin{Vmatrix}
\vartheta & \varrho \\
\varphi & \varpi
\end{Vmatrix}
\]

To produce a small matrix suitable for use in text, use the **smallmatrix** environment.

\[
\begin{pmatrix}
a & b \\
c & d
\end{pmatrix}
\]

To show the effect of the matrix on the surrounding lines of a paragraph, we put it here: \( \begin{pmatrix} a & b \\
c & d \end{pmatrix} \) and follow it with enough text to ensure that there will be at least one full line below the matrix.

---

Proof: page numbers may be temporary
\texttt{\textbackslash hdotsfor\{number\}} produces a row of dots in a matrix spanning the
given number of columns:

\[
W(\Phi) = \begin{vmatrix}
\frac{\varphi}{(\varphi_1, \varepsilon_1)} & 0 & \ldots & 0 \\
\frac{\varphi_{k_{n2}}}{(\varphi_2, \varepsilon_1)} & \frac{\varphi}{(\varphi_2, \varepsilon_2)} & \ldots & 0 \\
\frac{\varphi_{k_{n1}}}{(\varphi_n, \varepsilon_1)} & \frac{\varphi_{k_{n2}}}{(\varphi_n, \varepsilon_2)} & \ldots & \frac{\varphi_{k_{n,n-1}}}{(\varphi_n, \varepsilon_{n-1})} & \frac{\varphi}{(\varphi_n, \varepsilon_n)} \\
\end{vmatrix}
\]

The spacing of the dots can be varied through use of a square-bracket option,
for example, \texttt{\textbackslash hdotsfor[1.5]{3}}. The number in square brackets will be used
as a multiplier; the normal value is 1.

9.18. The \texttt{\textbackslash substack} command. The \texttt{\textbackslash substack} command can be used
to produce a multiline subscript or superscript: for example

\[
\sum_{\substack{0 \leq i \leq m \\
0 < j < n}} P(i, j)
\]

produces a two-line subscript underneath the sum:

(62) \hfil \mathop\sum\limits_{\begin{subarray}{l}
0 \leq i \leq m \\
0 < j < n
\end{subarray}} P(i, j)

A slightly more generalized form is the \texttt{subarray} environment which allows
you to specify that each line should be left-aligned instead of centered, as here: Maybe “... as
below”?

(63) \hfil \mathop\sum\limits_{\begin{subarray}{l}
0 \leq i \leq m \\
0 < j < n
\end{subarray}} P(i, j)

Proof: page numbers may be temporary
9.19. **Big-g-g delimiters.** Here are some big delimiters, first in \texttt{\smallsize}:

\[
\left( E_y \int_0^{t_\varepsilon} L_{x,y^x(s)} \varphi(x) \, ds \right)
\]

and now in \texttt{\Large size}:

\[
\left( E_y \int_0^{t_\varepsilon} L_{x,y^x(s)} \varphi(x) \, ds \right)
\]

\[\]

**References**


Proof: page numbers may be temporary


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